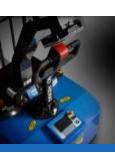


# Seegrid Industrial Mobile Robots: Using Vision Guidance for Navigation in Extraterrestrial Applications

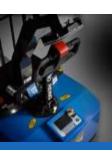
Space Manufacturing 14
October 30, 2010

Mitchell Weiss





- A Little History
- Application Space
- Technology
- Challenges
- Opportunities

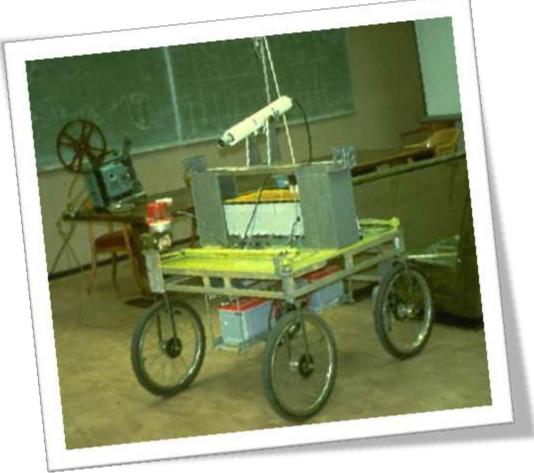


#### Industrial Mobile Robot

- Uses onboard intelligence to cooperatively move materials in an industrial work space
- No infrastructure modifications or additional equipment needed
- Leverages advances in computing power

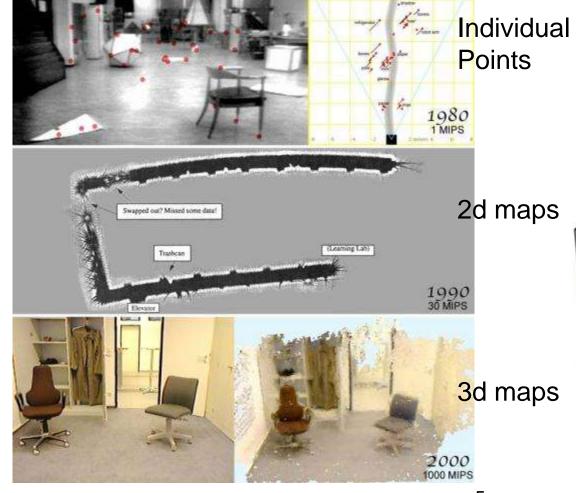
# Seegrid Beginnings







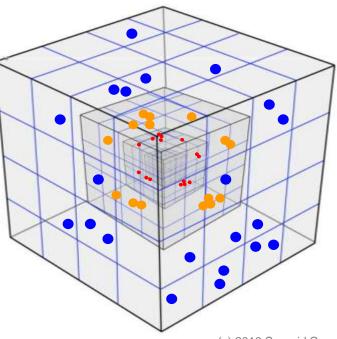
#### Vision Navigation to 3D Grids



**Points** 

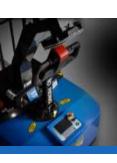
2d maps

3d maps

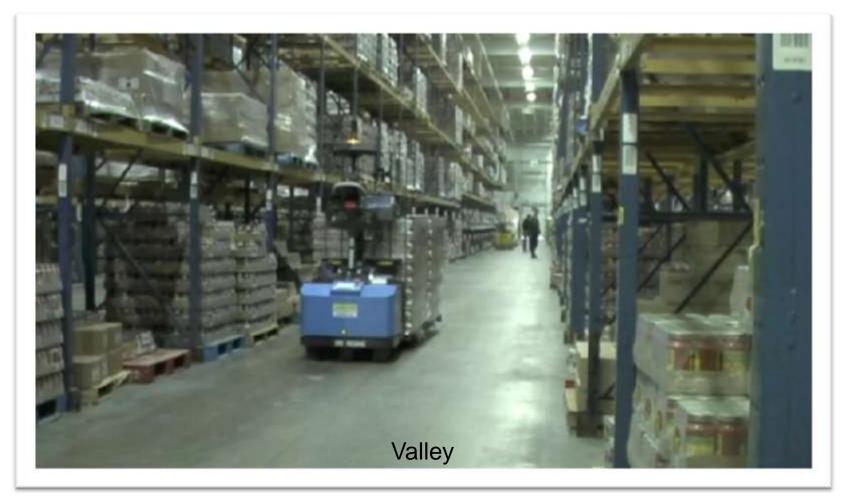


5





## Application Space: "Picking Aisle"





#### **Cross Aisle**









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#### **Bulk Warehouse**





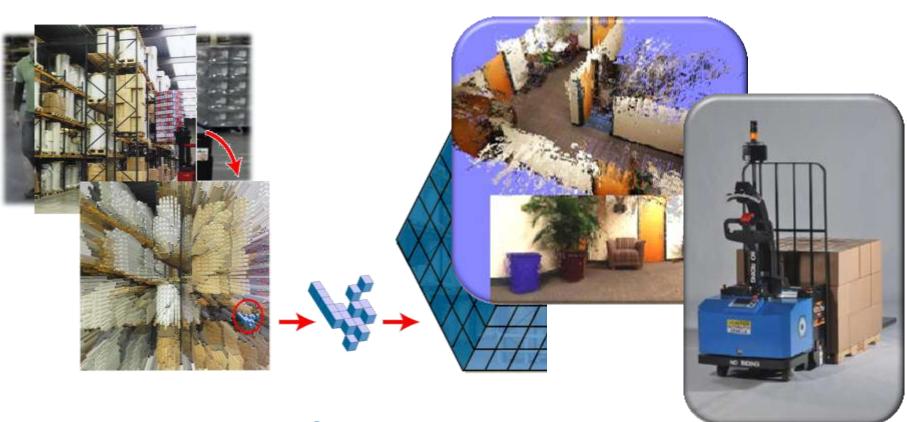
#### Narrow Aisle





#### How it Works

#### 2 -- Build Model



1 -- Walk Through, Collect Data

3- Then Work



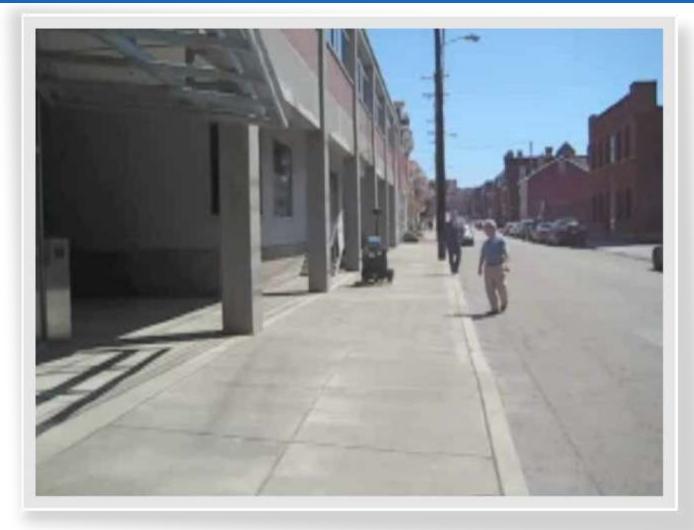
## Stereo Features



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# **Outdoor Testing**





#### Outdoor Guidance Research

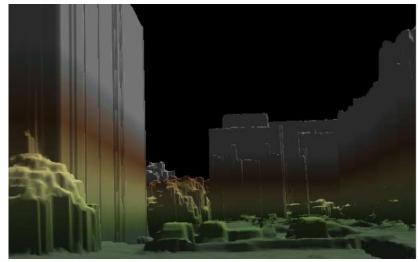


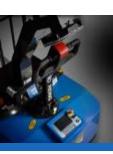




# Mapping from Independent Data







- No Localization Infrastructure (GPS, Beacons)
- Hostile Environment Mapping Challenge
- Variable Environment



- "Offline" Mapping
- Mission Planning
- Autonomous Operation and Exception Handling
- Variety of Environments



